

Characterisation of proton exchange membrane fuel cell (PEMFC) failures via electrochemical impedance spectroscopy

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Abstract

Two PEMFC failure modes (dehydration and flooding) were investigated using in situ electrochemical impedance spectroscopy (EIS) on a four-cell stack under load. The EIS measurements were made at different temperatures (70 and 80 °C), covering the current density range 0.1–1.0 A cm⁻², and the frequency range 0.1–2 × 10⁵ Hz. Dehydration and flooding effects were observed in the frequency ranges 0.5–10⁵ and 0.5–10² Hz, respectively.

We propose that impedance measurements at separate frequency ranges (or narrow bands thereof) can be used to distinguish between flooding and dehydration events. Similar approaches may be used to diagnose other important PEMFC failures.

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1. Introduction

For fuel cells to reach consumer products, the relationship between their performance, lifetime, and failure mechanisms must be understood. The known failure patterns must be translated into industrial and commercial standards, quality control protocols, and safety or recycling regulations. The experimental methods available for failure diagnosis, degradation characterisation, and durability assessment have been reviewed by Wilkinson and St.-Pierre [1], Laconti et al. [2], and Fowler et al. [3,4]. The techniques discussed by these authors consider several PEMFC performance indicators including output voltage, membrane resistance, reactant permeability, water management, and they focus on specific designs or components.

Independent of the specific materials, topologies, or configurations fuel cells are characterised by their dependence on

interfacial phenomena. The relevant physical processes (electron transfer, reactant diffusion, etc.) are controlled by the bulk properties of the different materials and, more importantly, by the interfacial characteristics between materials or phases. At each interface, the material properties change discontinuously and abruptly, and can become the limiting performance factors. Electrochemical impedance spectroscopy (EIS) is a technique especially well suited to characterise interfaces, and it can be used to characterise fuel cell performance non-invasively and in situ.

Although caution must be exercised in assigning physical processes to specific spectral features, EIS techniques provide powerful characterisation tools. Macdonald has published one of the best technical reviews available to date [5]. This review illustrates the progress made since Bauerle used EIS on zirconia–yttria compounds that can be used as the ionic conductors in solid-oxide fuel cells [6,7]. Since then, EIS measurements have also been made on phosphoric acid [8], molten carbonate [9], and direct methanol fuel cells [10,11]. More recently, EIS techniques in the context of PEMFC applications have resulted in a large number of publications [6–85]. A significant portion of these studies is devoted to materials development and component

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Nomenclature

Δt_{dry}	total drying time (s)
ΔZ	impedance ratio between normal and simulated failure conditions
j	current density (A m^{-2})
j_0	amplitude of ac current density perturbation (A cm^{-2})
j_{dc}	dc current density (A cm^{-2})
λ_{O_2}	oxidant stoichiometry
λ_{H_2}	fuel stoichiometry
R_{stack}	stack resistance ($\Omega \text{ cm}^2$)
T	temperature (K)
θ_0	phase angle difference under normal conditions ($^\circ$)
θ	phase angle difference between current and potential ($^\circ$)
t_{dry}	time along a drying curve (s)
V_s	output from FRA's signal generator (V)
V_{dc}	dc bias from FRA's signal generator (V)
V_{ac}	ac perturbation from FRA's signal generator (V)
\tilde{V}_k	complex potential across cell k ($k=1-4$) (V)
\tilde{V}_T	complex potential across stack (V)
\tilde{V}_Ω	complex potential across shunt resistor (V)
V_{app}	attenuated input voltage to load bank (V)
V_{in}	input voltage to load bank (V)
Z	impedance ($\Omega \text{ cm}^2$)
Z'	real impedance component
Z''	imaginary impedance component
Z_W	Warburg impedance ($\Omega \text{ cm}^2$)
Z_0	impedance under normal conditions ($\Omega \text{ cm}^2$)

optimisation (for new catalysts, membranes, etc). For example, Springer and co-workers have developed models describing the electrical properties of different material layers in a PEMFC cathode. Their efforts have yielded one of the most complete descriptions of porous gas diffusion layers (GDLs) [80], and the prediction of expected features in the relevant impedance spectra. According to the flooded agglomerate model, the impedance spectra should present three arcs: one at high frequencies due to the double layer capacitance (charging through the charge transfer resistance); a mid-frequency arc (caused by the agglomerate dynamics); another arc at low frequencies (due to oxygen diffusion through the thin film). Experimental validation of these models and the potential uses of EIS as a characterisation technique have also been reported [41,81]. The measured spectra usually show only one or two arcs in the Nyquist plots covering the frequency range from 10^{-1} to 10^5 Hz [28]. These results have also been related to specific operating parameters in operating PEMFCs. Diard et al. have reported on EIS measurements made on a single cell with a small active area (25 cm^{-2}) operating at 80°C under constant current load [17]. Their results show two depressed semi-circles, and large inductance effects at the high-frequency limit of the collected spectra (6.5 kHz). These effects and their causes are not discussed in detail.

The water content and ionic conductivity in Nafion and other membranes has also been the subject of EIS studies. Freire and Gonzalez have carried out studies on the impedance response of PEMFCs under varying humidification conditions [72]. The membrane materials, GDLs, and catalyst loadings were comparable to those used in the present work. The impedance measurement hardware, the imposed ac perturbation, and the reported frequency range (5 mHz to 20 kHz) were also similar to those considered here. Ciureanu and Roberge have described the potentiostatic measurements made on a single cell (active area = 25 cm^2) operating at 25°C [14,15,71]. They also justify the adoption of a two-electrode measurement technique (with the anode functioning as both the auxiliary and reference electrodes). These approaches were evaluated independently and considered appropriate for the galvanostatic measurements reported in this work (see Section 2). In another publication, these authors discuss the potential use of EIS as a detection technique for catalyst poisoning (CO on Pt and Pt/Ru alloys) [14]. Large inductive effects were present in the low- and high-frequency limits of the collected spectra (10^{-2} and 10^4 Hz, respectively). The application of IES techniques for practical failure detection has also received attention recently.

In this work we propose that the measured spectral features can yield important information on potential failure modes, and more specifically, that EIS techniques can be used to distinguish between different failures in a PEMFC stack under load. Our experimental investigation focuses on water management failures, and considers two extremes: the dehydration in the membrane-electrode-assembly (MEA), and the presence of excess humidifying or product water.

Membrane dehydration reduces the protonic conductivity which can be approximated by changes in ohmic resistances. In contrast, the impedances associated with mass transport (e.g., diffusion within the electrode layers) require simulation via distributed circuit elements whose response varies with frequency [59–61,63–65]. Based on this analysis, we hypothesised that each failure corresponds to impedance changes that are observable at different frequency ranges. The hypothesis was tested experimentally by simulating the two failures in a small PEMFC stack and measuring the EIS spectra before, during, and after a simulated failure.

2. Experimental materials and methods

Our stack consisted of four cells connected in series, and separated by water-heated compartments. Individual cell and overall stack impedances were measured with the stack under load as illustrated in Fig. 1. Unlike conventional designs with a common manifold, each cell in the stack had separate inlet and outlet ports for the reactants. With reference to the numerals in Fig. 1, the cells consisted of two graphite bipolar plates (1), separated by a membrane electrode assembly (2), whose properties have been summarised in Table 1. Lateral manifold plates (3) were fabricated to deliver the reactants to each cell individually. They were attached to alignment blocks perpendicular to the manifold planes. Gold-plated copper plates (4) were used to collect the electronic current from the stack anode, deliver it

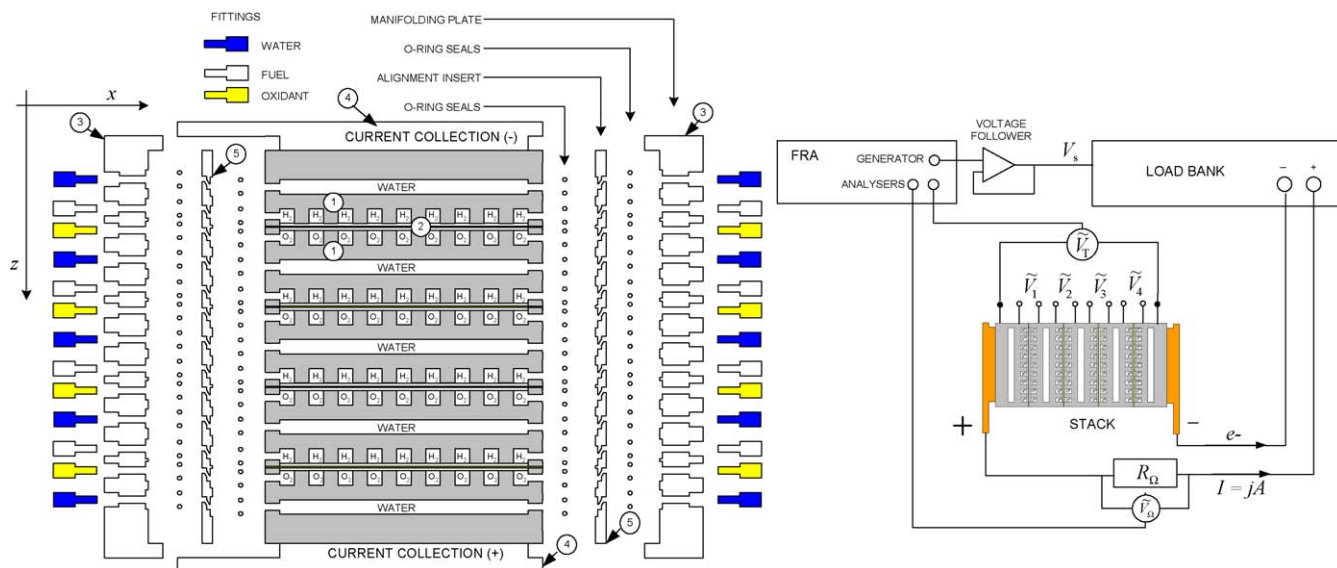


Fig. 1. The cross sectional view of the four-cell stack (left) and the functional modules required for impedance measurements (the illustration corresponds to the determination of Z_T).

to the load bank through a shunt resistor, and complete the circuit at the stack cathode. Four plastic inserts (5) were used to hold individual o-rings against each delivery port, and to accommodate small variations in MEA thickness. A pneumatic piston was used to control the stack sealing pressure along its longitudinal axis. This design made it possible to control the delivery and conditioning of reactants to individual cells, and to simulate single-cell failures without disturbing the steady state operation of the entire stack.

2.1. Membrane electrode assemblies (MEAs)

The MEA and single cell characteristics have been summarised in Table 1. The polymer area exceeded the active area

Table 1
Single cell properties and materials

	Value/description
MEA	
Gas diffusion layer (GDL) type	Carbon cloth
Ionic conductor	Nafion 115
Dry membrane thickness (m)	1.0×10^{-4}
Catalyst loading [anode] (cathode) (mg Pt cm ⁻²)	[0.4] (2.0)
Active area (m ²)	3.08×10^{-3}
Uncompressed GDL thickness (m)	4.5×10^{-4}
Bipolar plates	
Material	Graphite
Plate thickness (m)	6.35×10^{-3}
Flow field pattern	Single serpentine
Channel cross-sectional area [fuel] (oxidant) (m ²)	$[6.30 \times 10^{-4}] (8.22 \times 10^{-4})$
Channel length [fuel] (oxidant) (m)	[2.44] (1.77)
Pressure drop at 2, 4, and 6 SLPM [fuel] (oxidant) (psi)	[1.5, 3.5, 5.5] (0.5, 1.0, 2.5)

(approximately 30 cm²), and the extra polymer perimeter was used as the sealing surface for the inter-cell gaskets. Flooding and drying experiments were carried out using MEAs with ELAT/SS carbon cloth as the electrode substrate, and NafionTM 115 as the ionic conductor. The manufacturing techniques for these MEAs are described elsewhere [86].

2.2. Impedance measurements

A frequency response analyser (FRA) was connected to an electronic load as illustrated on the right of Fig. 1 (models 1255B from Solartron Analytical, and MCL488 from TDI-Dynaload, respectively). A voltage follower circuit was used to isolate grounds and unwanted current flow between the output signal from the FRA and the analog input to the load. The output signal, V_s , was the sum of a varying dc voltage (0–3 V dc), and an ac signal of small amplitude (5–20 mV rms):

$$V_s = V_{dc} + V_{ac} \sin(\omega t) \quad (1)$$

The steady state component, V_{dc} , controlled the dc current drawn from the stack (1 V = 10 A). The superimposed ac signal created a small, galvanostatic perturbation that generated voltage changes across a shunt resistor (\tilde{V}_Ω), each individual cell (\tilde{V}_k , $k=1-4$), and the overall stack (\tilde{V}_T). The frequency of this perturbation ranged from 0.5 Hz to approximately 200 kHz, and the high frequency limit was dictated by the cut-off frequency in the electronic load (20 kHz).

According to the load specifications, a frequency of 20 kHz in the control signal corresponds to an attenuation of –3 dB. However, we noted that the current perturbation amplitude was reduced, but not completely attenuated beyond this frequency. Even at higher attenuation rates (e.g., –12 dB/octave) the response amplitudes (\tilde{V}_Ω , \tilde{V}_k , $k=1-4$, and \tilde{V}_T) were still within the sensitivity range of the FRA (see Fig. 2). Therefore,

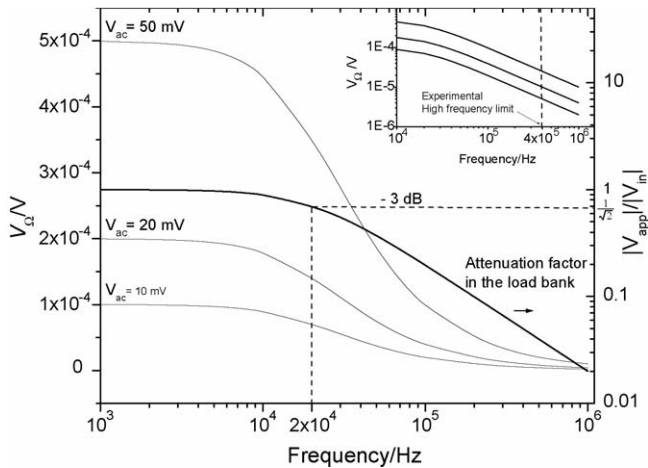


Fig. 2. The FRA sensitivity was sufficient to perform measurements beyond the load cut-off frequency (20 kHz) published by the manufacturer.

we were able to make meaningful and repeatable measurements beyond the high-frequency limit reported by the load manufacturer.

During a frequency sweep, the response across the shunt resistor, \tilde{V}_Ω , and the response from one of these components were measured concurrently and the corresponding impedance was calculated directly:

$$\tilde{Z}_x = \frac{\tilde{V}_x R_\Omega}{\tilde{V}_\Omega}, \quad x \in \{1, \dots, 4, T\} \quad (2)$$

Tildes indicate complex numbers that can be plotted as real and imaginary pairs on the Argand plane. In the discussion that follows, we use the notation Z' and Z'' for the real and imaginary parts of these pairs, respectively.

2.3. EIS limitations and experimental artefacts

Non-linearity and non-uniqueness represent two well-known limitations associated with EIS. In addition, the experimental

setup on working PEMFCs must minimise or eliminate other sources of error.

For example, the potential thermal effects on R_Ω , must be addressed by minimising heat transfer via conduction. In our configuration, the maximum ohmic heating dissipated by the shunt was approximately 1 W (at 32 A dc delivered by the stack). This heating rate was insufficient to alter the shunt resistance significantly. The variation of R_Ω with frequency was also measured by connecting both analyser channels to the shunt resistor, and performing a frequency sweep. The measured value for R_Ω was $10^{-3} \Omega$ in the frequency range 0.1 to $\sim 10^4$ Hz. At higher frequencies, capacitive effects were detectable but very small. These effects are likely due to stray capacitances in the lead wires (i.e., they are unlikely to originate from the resistor).

The magnetic fields in the neighbourhood of the current leads connected to the stack can be significant even at moderate loads (e.g., $50 \mu\text{T}$, 10 cm away from the centre of a cable carrying 5 A dc). As a result, inductive artefacts could be introduced by the position of the cables with relation to the stack. For example, placing the shunt resistor in the vicinity of a looping current cable resulted in large inductive loops in the impedance spectra at high frequencies (with correspondingly unphysical negative resistances). Other artefacts were generated by moving the cables or loosening the contacts between components (e.g., shunt to current cables, current cables to stack, etc). The importance of cell configuration in EIS measurements has received some attention [24], and the data reported in several publications includes signs of experimental artefacts. However, their causes and effects are seldom discussed in detail.

In this work, these effects were minimised by (i) fixing the cables and connections carefully, (ii) polishing and clamping all the metal contacts, (iii) twisting the large current leads to the electronic load, and (iv) maintaining equal lengths in the shielded, coaxial cables connected to the FRA. With these precautions, the impedance measurements were repeatable at each temperature and over the entire experimental frequency range ($0.5\text{--}2 \times 10^5$ Hz).

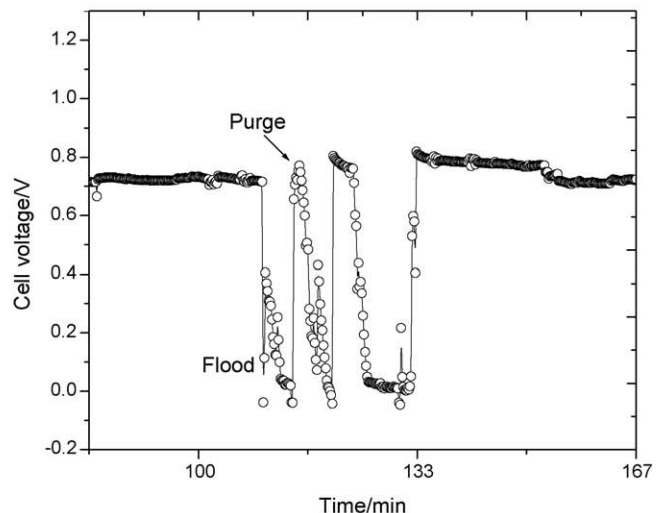
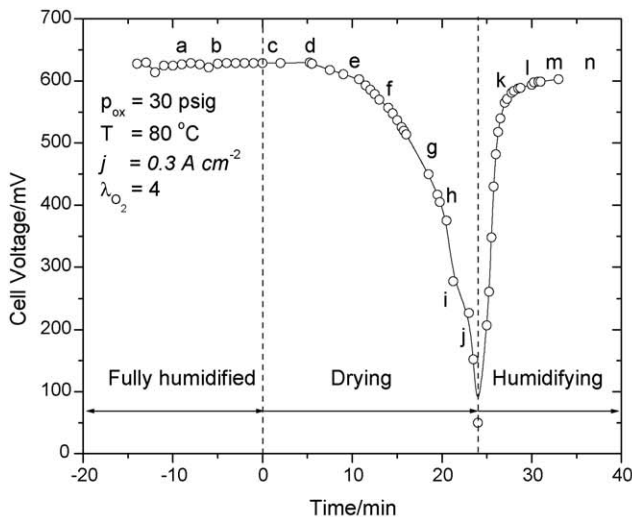


Fig. 3. The experimental curves for dehydration (left) and flooding (right). Points a, b, . . . , n on the dehydration curve correspond to the collected spectra.

3. Failure simulation

Dehydration was simulated by switching the oxidant in one cell between saturated and dry air streams at the same temperature (while maintaining constant humidification conditions in the remaining cells). The dehydrating cell and overall stack potentials were monitored while maintaining the other experimental parameters constant (temperature, pressure, gas flow, current density, etc.). EIS spectra were collected as the cell potential decreased and the varying spectra were compared to the spectrum collected prior to reactant switching (see Fig. 3). The drying process was allowed to continue until the cell potential dropped below 100 mV. At this point the oxidant streams were switched again and the cell re-humidified. At low current densities (e.g., $j = 0.1, 0.2 \text{ A cm}^{-2}$) the reactant flows are smaller and the resulting drying curves progressed with increasingly negative slopes (i.e., different potential drop rates). This behaviour can be attributed to the water removal from different layers within the MEA: at the beginning of a dehydration experiment, the excess water in the flow field channels and the surface of the GDL is removed first. As the drying process continues, water is removed from the porous GDL. In the final stages of dehydration, water is removed directly from the membrane and the dehydration process occurs more rapidly. At low current densities, irreversible membrane damage will occur in the final stages of a dehydration failure (thereby providing a few minutes for recovery measures). At higher current densities such as those required by automotive applications, the reactant flows are larger and the potentially irreversible damage occurs more rapidly. The time available to take corrective measures is thus reduced under these conditions.

Flooding failures were simulated by interfering with the oxidant flow downstream from an individual cell within the stack (thereby altering the reactant stoichiometry). Special attention was devoted to the cathode flows because the flooding effects are exacerbated by the presence of product water (in addition to the water carried by the saturated oxidant). EIS spectra were collected before and after flooding.

A flooding event consisted of a sudden drop in cell potential, followed by an intermittent potential profile (shown on

the right side of Fig. 3). Unlike the features in the dehydration curves, the transitions between normal and flooded conditions were sudden. Data collection between states was difficult due to physical limitations in the flow controls. Consequently, and unlike the dehydration events, a flooding failure was very difficult to control. These limitations and potential improvements to the experimental techniques are being considered in the design of new hardware. The following paragraphs discuss the trends in the experimental results.

4. Results and discussion

Fig. 4 shows the typical polarisation curves obtained with the stack under steady state operation and with one cell under simulated failure (cell 2 under flooding). As expected, the sum of the measured impedances from each cell was equal to the overall stack impedance measured following the experimental setup in Fig. 1.

The experimental hardware made it possible to simulate failures in one cell without interrupting the steady state operation of the overall stack. A single cell failure had an effect on the performance of the stack and adjacent cells (e.g., by establishing small temperature gradients from cell to cell). However, the impedance measured across the cell under simulated failure was the largest contribution to the measured stack impedance. Although the cell impedances were measured individually, we report on the overall stack impedance (with one cell failing) because we consider that this is most practical implementation for a future detection technique or device (e.g., a two- or four-wire measurement across an entire stack instead of individual cell monitoring).

Fig. 5 shows the typical spectra collected on the stack with all the cells operating under normal conditions (at time = t_0) and with one cell operating under progressively more dehydrated conditions (at time = $t_{\text{dry}} > t_0$). This sequence also illustrates the graphical conventions used to report and summarise all the data hereinafter.

Unless otherwise indicated, the stack impedance was measured in the frequency range $0.5\text{--}2 \times 10^5 \text{ Hz}$, using the components listed in Table 1, and under the experimental conditions listed in Table 2. The secondary plots superimposed on the upper

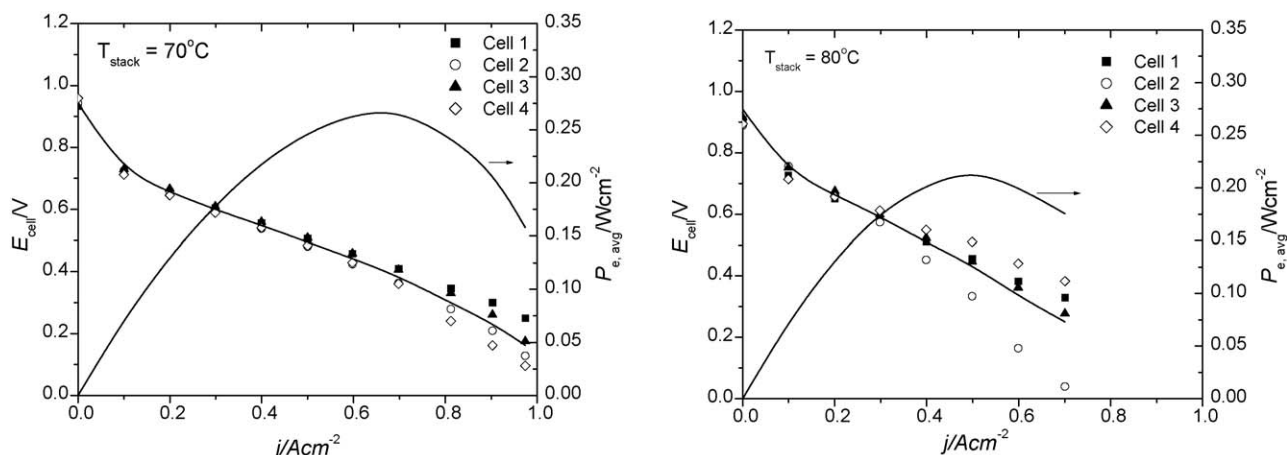


Fig. 4. The polarisation curves for the stack under steady state operating conditions (left) and with cell 2 under simulated flooding (right).

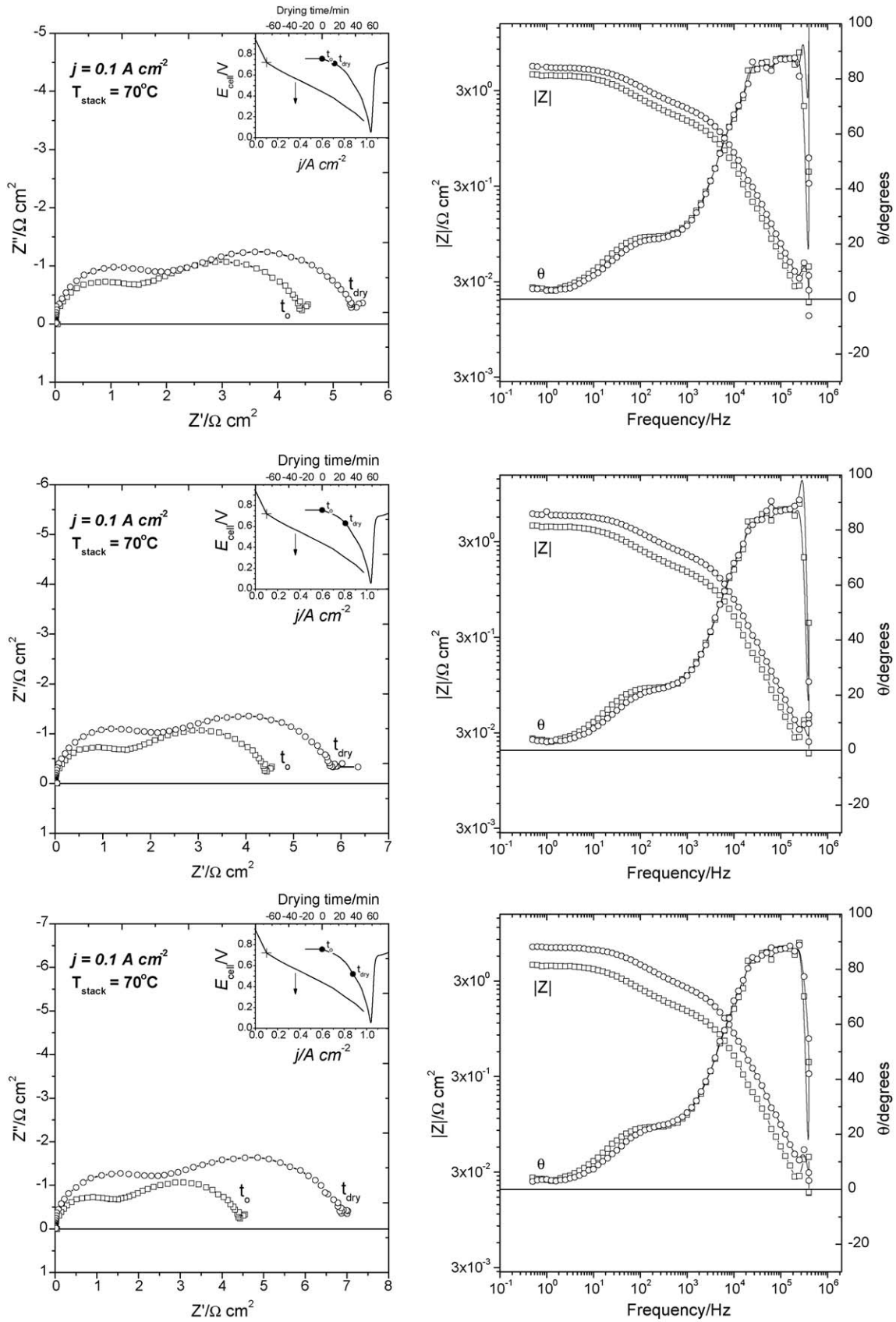


Fig. 5. Typical sequence of collected stack spectra under simulated dehydration in one cell.

Table 2
Experimental conditions

	Dehydration	Flooding
Fuel pressure (psig)	30	30
Oxidant pressure (psig)	30	30
Stack temperature (°C)	70	70
Humidification temperature [anode] (cathode) (°C)	$[T_{\text{stack}} + 10]$ ($T_{\text{stack}} + 10$)	$[T_{\text{stack}} + 10]$ ($T_{\text{stack}} + 10$)
Fuel stoichiometry	2	2
Oxidant stoichiometry	4	4–0
Longitudinal sealing pressure (psi)	120	120

right corner of the Argand planes provide two pieces of information: (i) they indicate the cell's operating point at the beginning of a simulated failure event (i.e., the point on the polarisation curve plotted on their bottom and left axis) and (ii) they show the points along the dehydration or flooding curves that varied as each experiment progressed.

Similar measurements were made at higher current densities and different temperatures. For brevity, the measurements under dehydration at illustrative current densities have been summarised by Fig. 6. Furthermore, the Bode plots are not included explicitly in this figure or in the remaining impedance spectra reported here. In all cases, the complex data on the Nyquist plots are equivalent.

As illustrated in Fig. 6, the dehydration experiments revealed an overall and monotonic increase in the stack's impedance as the failing cell became progressively more dehydrated (i.e., from point a to point f along the dehydration curve inset in Fig. 6). The salient feature during the dehydration experiments was the

increase in the stack impedance across the entire experimental frequency range (including the high frequency range above a few kHz). These results are consistent with impedance changes dominated by an increase in the ohmic resistance at the membrane.

Larger current loads required larger reactant flows with larger drying rates, and correspondingly shorter drying times. Consequently, the number of spectra collected between drying events was progressively smaller as the current load increased. The spectra collected do not correspond to a single point on the drying curves, but rather to an interval defined by the time required to collect the spectrum. Depending on the number of frequencies per decade and the low frequency limits, the collection times ranged from tens of seconds to a few minutes.

The recovery time upon re-humidification was too short to collect multiple spectra between fully dehydrated and fully re-humidified conditions (e.g., between points f and g in Fig. 6). To prevent ohmic overheating and potential irreversible damage to the membrane, the drying cell was always prevented from reaching potentials below 20 mV dc. This required rapid switching from dry to humidified oxidant streams.

The results under typical flooding simulations are summarised in Fig. 7. The simulated failures produced no variations in the high-frequency arcs of the measured impedance spectra. These results are consistent with constant membrane humidification between normal and flooded conditions (i.e., the membrane resistance corresponds to fully humidified conditions in both cases).

The measured flooding effects on impedance were small but detectable (e.g., the change in magnitude is smaller than $1 \Omega \text{ cm}^2$ at $j = 0.1, 0.3,$ and 0.5 A cm^{-2}). Unlike the dehydration effects, the flooding variations were not present over the entire

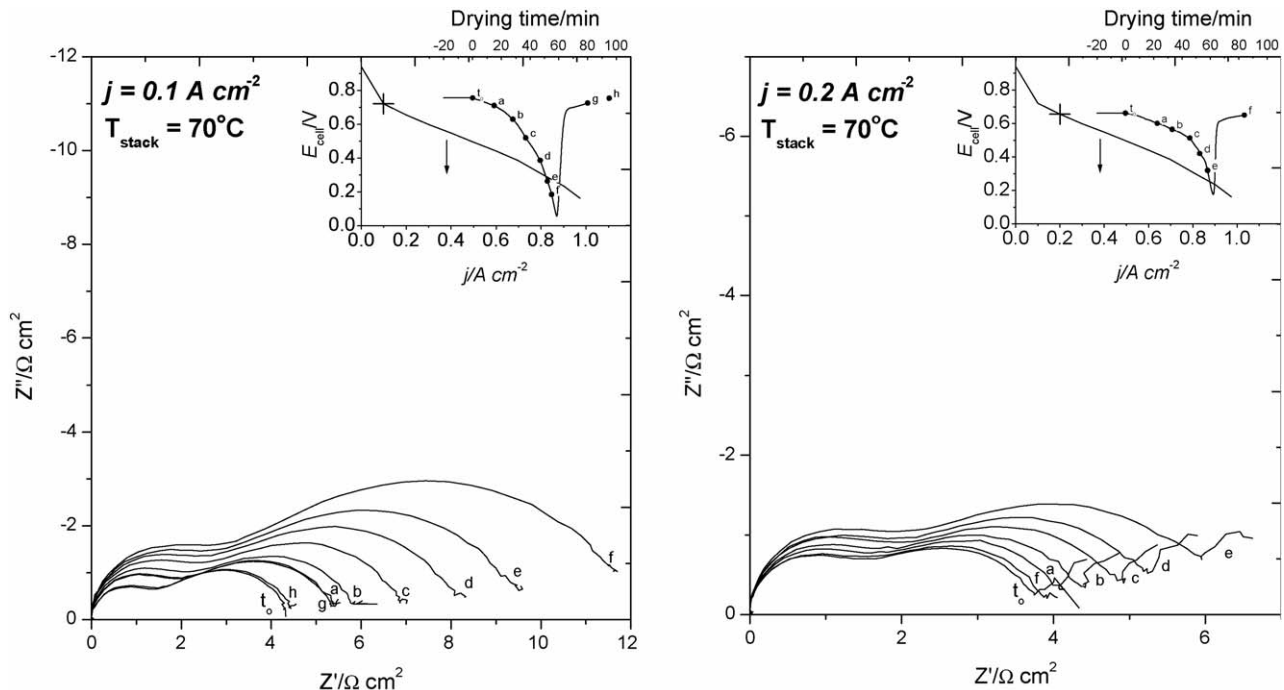


Fig. 6. Measured stack impedance with one cell under dehydration at 70°C . $j = 0.1 \text{ A cm}^{-2}$ (left) and $j = 0.2 \text{ A cm}^{-2}$ (right).

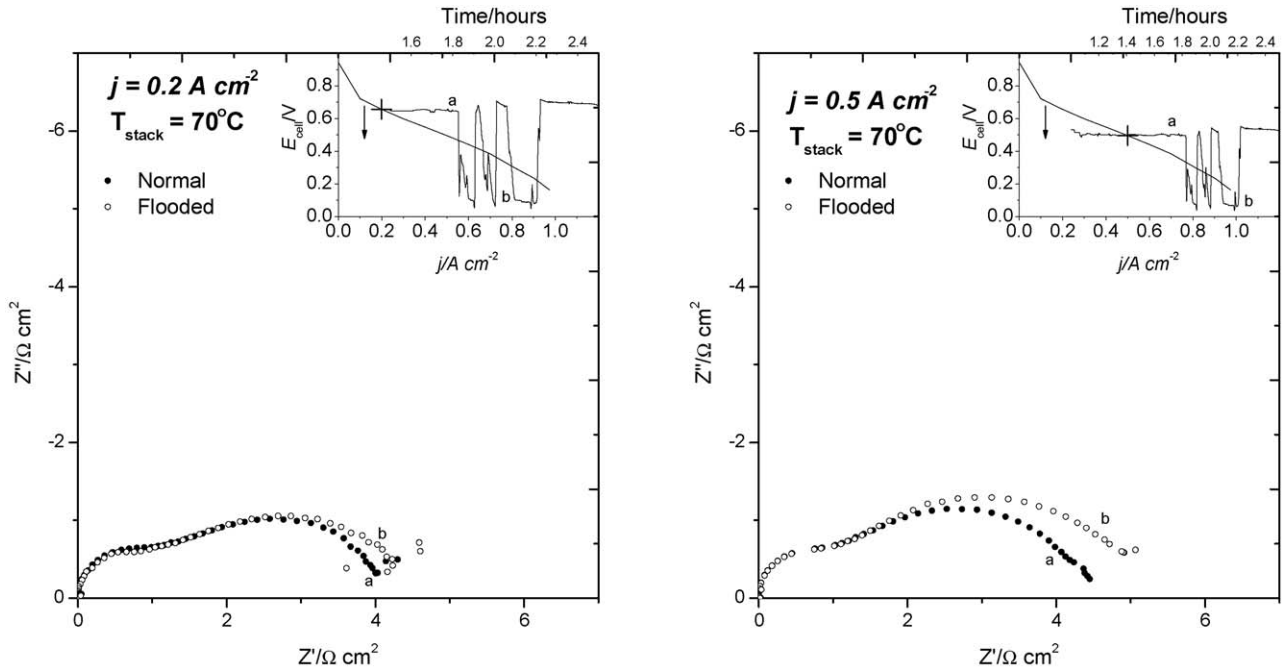


Fig. 7. Measured stack impedance with one cell under simulated flooding at 70 °C. $j=0.2 \text{ A cm}^{-2}$ (left) and $j=0.5 \text{ A cm}^{-2}$ (right).

experimental frequency range, and they were only detected between 0.5 and 10^2 Hz. Although it is the focus of current efforts, our objective in this work was not to provide a detailed investigation of the underlying physical phenomena causing the changes in impedance. We propose that by monitoring these changes over different frequency ranges (or narrow bands thereof), it may be possible to detect and distinguish two or more failure modes.

Practical and inexpensive detection systems are unlikely to measure real and imaginary impedance components separately, or to cover wide frequency ranges. Measuring the variation of impedance amplitude- or phase-angle ratios over narrow frequency bands may be simpler and more economical. Fig. 8 has been used to summarise the change in the impedance magnitude with frequency. This change was quantified by the ratio $\Delta Z = |Z|/|Z_0|$, where Z corresponds to the overall stack

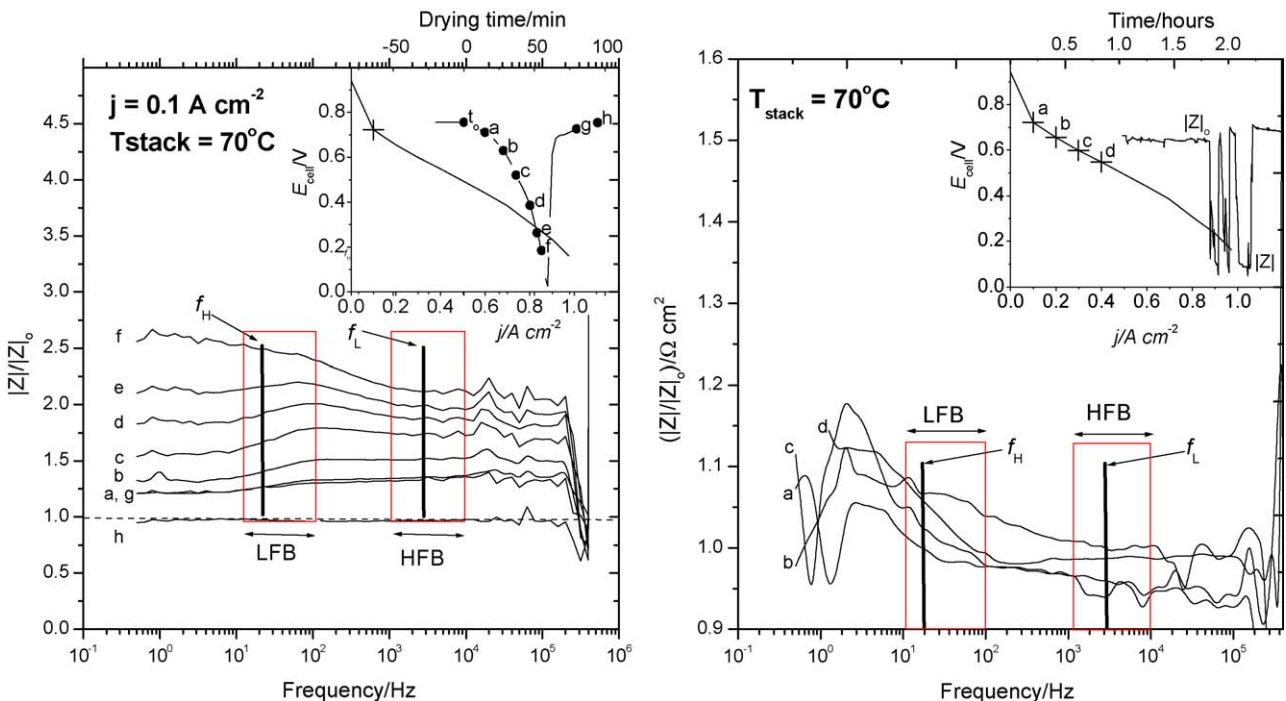


Fig. 8. Measured change in impedance magnitude ratios for dehydrating (left) and flooding conditions (right). Concurrent impedance measurements at high- and low-frequency bands (HFB and LFB) can be used to distinguish between two failure modes.

impedance measured along the drying curves (with once cell failing), and Z_0 corresponds to the stack impedance measured under normal operating conditions (i.e., the impedance magnitude prior to the simulated failure in one cell).

As illustrated, the amplitude ratios under dehydrating conditions are large and relatively constant over a wide frequency range, and as expected, the magnitude ratio calculated from the measurements before dehydration and after recovery was very close to unity. In Fig. 8 two arbitrary frequency bands have been indicated. A single frequency in each band (f_L and f_H) could suffice to diagnose the failure: large impedance variations ($>5\%$) at high frequencies ($f > 103$ Hz) can be associated with dehydration. Smaller variations ($<10\%$) at low frequencies without concurrent changes at high frequencies can be associated with flooding.

The net water transport rates within the MEA are the result of complex and highly coupled mechanisms. Further experiments are required to elucidate these mechanisms, and the individual phenomenological contributions to the impedance spectrum. The design of such experiments is the focus of ongoing efforts at our laboratories. With measurements at carefully chosen frequency combinations, Harrington and Mérida have proposed that these techniques may be sufficient for the specifications of practical detection hardware and techniques [87].

5. Conclusions

EIS measurements have been used to characterize the macroscopic effects of dehydration and flooding on the impedance of PEMFCs. The two failure modes were simulated on individual cells within a four-cell stack under load. The dehydration effects were measurable over the frequency range 0.5–100 kHz, while the flooding effects were measurable in the frequency range 0.5–100 Hz.

These results illustrate that separate or concurrent impedance measurements in distinct frequency ranges (or narrow bands thereof) may be used to identify the two failure modes semi-instantaneously (the detection time being limited by the response or acquisition time in an eventual diagnosis device).

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